NAG Fortran Library Routine Document

G05EAF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

G05EAF sets up a reference vector for a multivariate Normal distribution with mean vector a and covariance matrix C, so that G05EZF may be used to generate pseudo-random vectors.

2 Specification

SUBROUTINE G05EAF(A, N, C, IC, EPS, R, NR, IFAIL)INTEGERN, IC, NR, IFAILrealA(N), C(IC,N), EPS, R(NR)

3 Description

When the covariance matrix is non-singular (i.e., strictly positive-definite), the distribution has probability density function

$$f(x) = \sqrt{\frac{|C^{-1}|}{(2\pi)^n}} \exp\left\{-(x-a)^T C^{-1}(x-a)\right\}$$

where n is the number of dimensions, C is the covariance matrix, a is the vector of means and x is the vector of positions.

Covariance matrices are symmetric and positive semi-definite. Given such a matrix C, there exists a lower triangular matrix L such that $LL^T = C$. L is not unique, if C is singular.

G05EAF decomposes C to find such an L. It then stores n, a and L in the reference vector r for later use by G05EZF. G05EZF generates a vector x of independent standard Normal pseudo-random numbers. It then returns the vector a + Lx, which has the required multivariate Normal distribution.

It should be noted that this routine will work with a singular covariance matrix C, provided C is positive semi-definite, despite the fact that the above formula for the probability density function is not valid in that case. Wilkinson (1965) should be consulted if further information is required.

4 References

Knuth D E (1981) *The Art of Computer Programming (Volume 2)* (2nd Edition) Addison-Wesley Wilkinson J H (1965) *The Algebraic Eigenvalue Problem* Oxford University Press, Oxford

5 Parameters

1:	A(N) – <i>real</i> array	Input
	On entry: the vector of means, a, of the distribution.	
2:	N – INTEGER	Input
	On entry: the number of dimensions, n, of the distribution.	
	Constraint: $N > 0$.	

Input

Input

Input

Output

Input

3: C(IC,N) – *real* array

On entry: the covariance matrix of the distribution. Only the upper triangle need be set.

4: IC - INTEGER

On entry: the first dimension of the array C as declared in the (sub)program from which G05EAF is called.

Constraint: $IC \ge N$.

5: EPS – *real*

On entry: the maximum error in any element of C, relative to the largest element of C.

Constraint: $0.0 \le EPS \le 0.1/N$.

If EPS is less than *machine precision*, *machine precision* is used.

6: R(NR) - real array

On exit: the reference vector for subsequent use by G05EZF.

7: NR – INTEGER

On entry: the dimension of the array R as declared in the (sub)program from which G05EAF is called.

Constraint: $NR \ge ((N + 1) \times (N + 2))/2$.

8: IFAIL – INTEGER

On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.

On exit: IFAIL = 0 unless the routine detects an error (see Section 6).

For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.

6 Error Indicators and Warnings

If on entry IFAIL = 0 or -1, explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

IFAIL = 1

On entry, N < 1.

IFAIL = 2

On entry, $NR < ((N + 1) \times (N + 2))/2$.

IFAIL = 3

On entry, IC < N.

IFAIL = 4

 $\begin{array}{ll} \text{On entry,} \ \text{EPS} < 0.0, \\ \text{or} \qquad \text{EPS} > 0.1/\text{N}. \end{array}$

Input/Output

IFAIL = 5

The covariance matrix C is not positive semi-definite to accuracy EPS.

7 Accuracy

The maximum absolute error in LL^T , and hence in the covariance matrix of the resulting vectors, is less than $(n \times \max(\text{EPS}, \epsilon) + (n+3)\epsilon/2)$ times the maximum element of *C*, where ϵ is the *machine precision*. Under normal circumstances, the above will be small compared to sampling error.

8 Further Comments

The time taken by the routine is of order n^3 .

It is recommended that the diagonal elements of C should not differ too widely in order of magnitude. This may be achieved by scaling the variables if necessary. The actual matrix decomposed is $C + E = LL^T$, where E is a diagonal matrix with small positive diagonal elements. This ensures that, even when C is singular, or nearly singular, the Cholesky Factor L corresponds to a positive-definite covariance matrix that agrees with C within a tolerance determined by EPS.

9 Example

The example program prints five pseudo-random observations from a bivariate Normal distribution with means vector

```
\begin{bmatrix} 1.0\\ 2.0 \end{bmatrix}
```

and covariance matrix

```
\begin{bmatrix} 2.0 & 1.0 \\ 1.0 & 3.0 \end{bmatrix},
```

generated by G05EAF and G05EZF after initialisation by G05CBF.

The generator mechanism used is selected by an initial call to G05ZAF.

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
GO5EAF Example Program Text
      Mark 20 Revised. NAG Copyright 2001.
*
      .. Parameters ..
      INTEGER
                       N, IC, NR
                        (N=2, IC=N, NR=(N+1)*(N+2)/2)
      PARAMETER
      INTEGER
                       NOUT
     PARAMETER
                       (NOUT=6)
      .. Local Scalars ..
*
     INTEGER
                       I, IFAIL, J
      .. Local Arrays ..
                       A(N), C(IC,N), R(NR), Z(N)
     real
      .. External Subroutines ..
     EXTERNAL
                       GO5CBF, GO5EAF, GO5EZF, GO5ZAF
      .. Executable Statements ..
      CALL G05ZAF('O')
      WRITE (NOUT, *) 'GO5EAF Example Program Results'
      WRITE (NOUT, *)
      A(1) = 1.0e0
      A(2) = 2.0e0
      C(1,1) = 2.0e0
      C(2,2) = 3.0e0
      C(1,2) = 1.0e0
```

```
C(2,1) = 1.0@0
CALL GO5CBF(0)
IFAIL = 0
*
CALL GO5EAF(A,N,C,IC,0.01@0,R,NR,IFAIL)
*
DO 20 I = 1, 5
IFAIL = 0
CALL GO5EZF(Z,N,R,NR,IFAIL)
WRITE (NOUT,99999) (Z(J),J=1,N)
20 CONTINUE
STOP
*
99999 FORMAT (1X,2F10.4)
END
```

9.2 Program Data

None.

9.3 Program Results

G05EAF Example Program Results

1.7697	4.4481
3.2678	3.0583
3.1769	2.3651
-0.1055	1.8395
1.2933	-0.1850